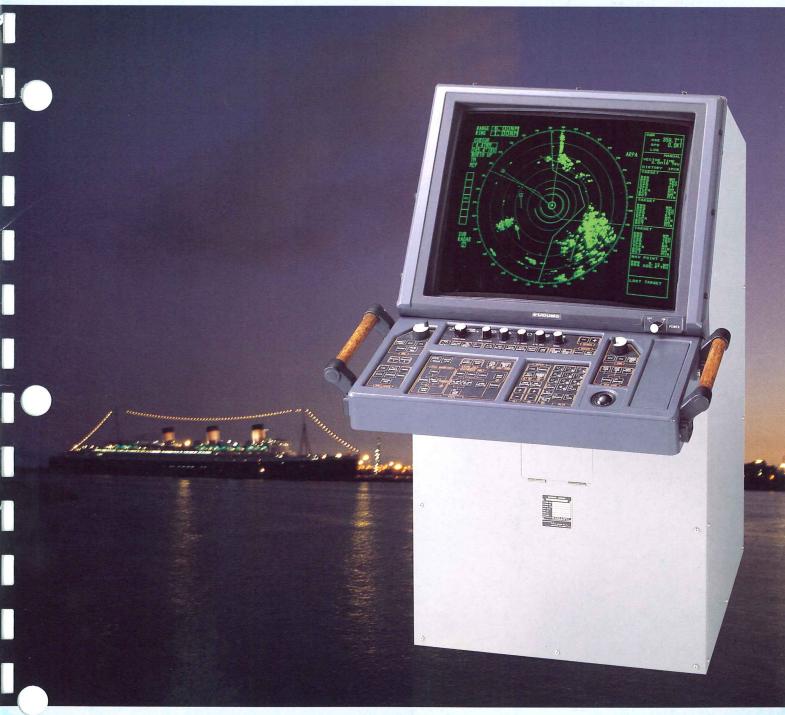


FURUNO®

AUTOMATIC RADAR PLOTTING AID

Models FAR-2800 series

Add-on ARPA Model FA-2800





The future today with FURUNO's electronics technology.

FURUNO ELECTRIC CO., LTD.

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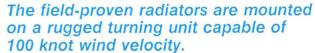
Catalogue No.R-117

TRADE MARK REGISTERED MARCA REGISTRADA

FURUNO's Second Generation Da ylight ARPA Offering Quality, High-resolution Picture W Ith Unrivalled Target Tracking Capability

- 28" diagonal CRT presents radar picture of 360 mm effective diameter with alphanumeric data area around it
- Acquires up to 20 targets automatically plus up to 20 targets manually, or all 40 targets manually
- Movement of tracked targets shown by true vectors and plots, or relative vectors and plots (Vector length 1 to 99 min. selected in 1 min. steps)
- On-screen digital readouts of range, bearing, course, speed, CPA (Closest Point of Approach), TCPA (Time to CPA), BCR (Bow Crossing Range) and BCT (Bow Crossing Time) of up to 3 target ships as well as own ship's speed and course

- Setting of nav lines, buoy marks and other symbols to enhance navigation safety
- Audible and visual alarms against threatening targets coming into operatorselected CPA/TCPA limits, lost targets, targets in two guard rings; visual alarm against system failure and target full situation
- Easy operation by combination of tactile backlit touchpads, a trackball and rotary controls
- Stylish display designed for self-standing or panel mounting
- Options: A built-in Interswitch RJ-6 and a built-in Gyro Interface GC-6



The new FAR-2800 series of ARPA's are the results

of combination of the FURUNO's many years of

experience in the marine field and the advanced computer technology. The FAR-2800 series are designed to fully meet the exacting rules of the

International Maritime Organization (IMO) for

The display unit employs a 28" diagonal highresolution green-phosphor CRT. It provides an effective radar picture of 360 mm diameter leaving

installations on all classes of vessels.





radiator and a powerful gearbox. On FAR-2830S, the transceiver is built in the gearbox.

The S-band antenna consists of a 12-ft

X-band Antenna for FAR-2822, 2822X, 2852X



The X-band antenna consists of a selectable 6.5-, 8- or 10-ft radiator and a powerful gearbox. On FAR-2822, the transceiver is built in the gearbox.

Modular Display Unit

Modular type display is available for mounting on table or in bridge console. The control head can be installed at any convenient place for operation up to 5 meters from the processor unit, and the processor unit may be installed in a hide-away place.





sufficient space for on-screen alphanumeric data. Target detection is enhanced by the sophisticated signal processing technique such as multi-level quantization (MLQ), echo stretch, echo average, and a built-in radar interference rejector. And an audible and visual guard zone alarm is provided as standard.

Other ship's movement can be visually assessed by echo trails or echo plots in addition to vectors and textual readouts.

On-screen data readouts include CPA, TCPA, range, bearing, speed/course of own ship and up to 3 targets. The ARPA functions include automatic acquisition of up to 20 targets plus manual acquisition of up to 20 targets, or manual acquisition of all 40 targets. In addition, the ARPA features display of a traffic lane, buoys, dangerous points, and other important reference points.

MODELS include:

ARPA's	Basic Specs.
FAR-2822	X-band, 25 kW, TR up
FAR-2822X	X-band, 25 kW, TR down
FAR-2852X	X-band, 50 kW, TR dowr
FAR-2830S	S-band, 30 kW, TR up
FAR-2832S	S-band, 30 kW, TR dowr
FAR-2862S	S-band, 60 kW, TR dowr
FA-2800	Add-on ARPA

Modular Type (separation type) available.

NAVIGATION FAIRWAYS, NAVIGATION POINTS

To help you maneuver the ship in the critical area, two nav lines and five nav points can be drawn. Each nav line may be a straight line or string of lines containing a maximum of five vertexes (corners). Five nav points can be registered to represent buoys or other important nav reference, and a selected point is displayed for readout.



Range/bearing to nav point from own ship

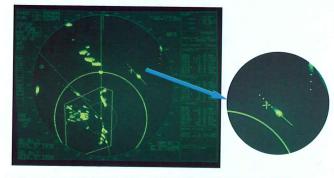
PARALLEL INDEX LINES

An electronic parallel cursor is useful for navigation maintaining a constant distance between own ship and a coastline or a reference. The cursor comprises 5 (0.5 and 0.75 nm scales) or 6 parallel lines (1.5 nm scale and above) in coincidence with the fixed range rings. (In regular version, the number of the lines is adjustable between 3 and 12)



ECHO TRAIL

Available on ARPA and Radar modes. Course and speed of other targets can be intuitively assessed by low intensity trail painted along their courseline. Interval is selected from 30 sec, 1 min, 3 min, or continuous.



AUTO ACQUISITION SUPPRESSION LINES

To protect the processor from overload or miscalculation, non-auto tracking zones can be established by 3 lines and a circle. Each line can be a straight line or a string of lines containing a maximum of five vertexes, fixed on land or ship. Acquisition circle is adjustable at 0.3 nm or more to avoid sea clutter. The lines are gyro stabilized so that frequent adjustment is not required.



GUARD RING, GUARD ZONE

Two guard rings are available between 0.2 and 32 nm with a width of 0.5 nm, in sector or full circle on ARPA mode. Targets coming into the ring from outside are marked with inverse triangles (∇). A guard zone is additionally available on ARPA and Radar modes to alert target by flashing.



TRIAL MANEUVER

Shows the likely consequences of proposed changes of own ship's speed or course. The ARPA simulates the future positions and speed/course of the nearby targets after the operator-selected time delay and new resulting CPA/TCPA is indicated on screen. If that CPA/TCPA is unsatisfactory, various trial courses, trial speed and delay time can be entered until the safe course and speed are found.



Trial speed course delay time

TARGET ACQUISITION

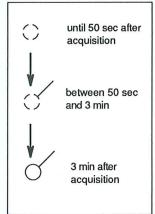
The ARPA acquires up to 20 targets automatically plus up to 20 targets manually, or all 40 targets manually. The FURUNO's exclusive advanced auto-tracking circuit assures reliable target acquisition and tracking.

In the automatic acquisition mode, the closest 20 targets within 0.3 and 32 nm are automatically acquired. Other targets within 32 nm range are continuously monitored, and if one of the monitored targets comes closer than one of the 20 targets being tracked, the ARPA will cancel tracking the farthest one and the new target will be acquired.

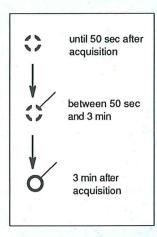
If an important target automatically acquired approaches the suppression area, it can be changed to manual acquisition; thus the target can continue to be tracked beyond the limit line. In this case, the ARPA symbol will change from a thin circle to a heavy circle.

Marks of acquired target changes in the following sequences:

Automatically acquired target

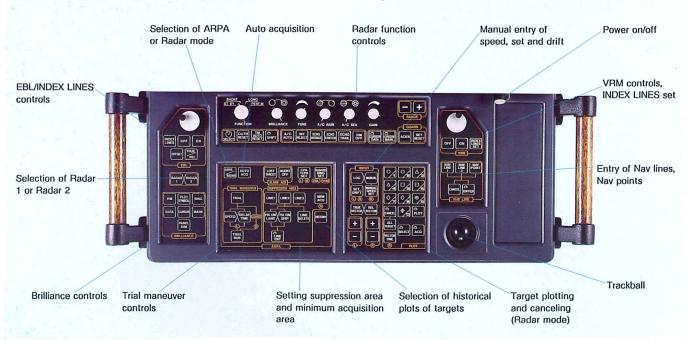


Manually acquired target



Easy-to-control

The combination of push buttons, rotary controls, and trackball allows easy and intuitive operation. For the modular (separation) type, the control head comes with 5 m cable from the processor unit.



Performance Monitors PM-30, PM-50 (option)

To meet IMO requirements, the performance monitor is mandatory on Convention ships. The PM-30 (X-band) and PM-50 (S-band), working as a low-power transponder, check radar transmitter and receiver circuits under normal radar operating condition. The unit is easily mounted behind the antenna and no modification in the radar unit is required.

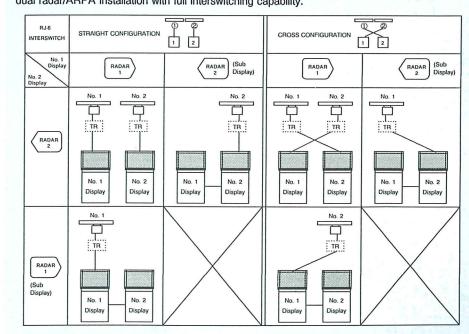
PM-30: X-band PM-50: S-band



Radar Interswitch Unit RJ-6 (option)

The FAR-2800 series is provided with an interface for an extra radar signal.

The RJ-6, which is built in the display unit (or in the processor unit on modular type), allows dual radar/ARPA installation with full interswitching capability.



SPECIFICATIONS OF FAR-2800 series, FA-2800

ANTENNA RADIATORS (not provided for FA-2800)

Slotted waveguide array 1. Type

6.5'(XN3)8'(XN4A) 10'(XN5A) 12'(SN7AF)

2. Beamwidth X-band S-band 1.23° 0.95° 0.75° 1.9° Hor: 25° 20° 20° 25° Vert:

3. Sidelobe Attenuation

Within ± 10°: 24 dB 28 dB 26 dB 25 dB Outside ± 10°: 30 dB 32 dB 30 dB 30 dB

4. Polarization Horizontal

26 rpm (60 Hz) or 21 rpm (50 Hz) 5. Rotation

Relative wind 100 knots 6. Wind Load

RF TRANSCEIVER (not provided for FA-2800)

Contained in the gear box on FAR-2822/2830S

Contained in the transceiver unit on FAR-2822X/2852X/2862S

1. Frequency

FAR-2822, FAR-2822X: 9410 ±30 MHz

FAR-2852X: 9415 ±30 MHz

FAR-2830S, FAR-2832S, FAR-2862S: 3050 ±30 MHz

2. Output Power

FAR-2822, FAR-2822X: 25 kW

FAR-2852X: 50 kW

FAR-2830S, FAR-2832S: 30 kW

FAR-2862S: 60 kW

3. Pulselength/PRR

0.08 µs, 2200 Hz (0.25, 0.5 nm)

0.08/0.3 (or 0.2*) µs, 2200/1100 Hz (0.75, 1.5 nm)

0.3 (or 0.2*)/0.6 µs, 1100/600 Hz (3 nm)

0.6/1.2 µs, 600 Hz (6, 12, 24 nm)

1.2 µs, 600 Hz (48 nm)/500 Hz (120 nm)

* FAR-2852X and FAR-2862S

60 MHz, Logarithmic

Bandwidth: 28 MHz (short pulse), 3 MHz (med/long pulse)

5. Duplexer Ferrite circulator with limiter diode

6. Noise Figure

FAR-2822, FAR-2822X, FAR-2852X: 6 dB nominal

FAR-2830S, FAR-2832S: 4 dB nominal

FAR-2862S: 4.5 dB nominal

DISPLAY UNIT

1. Type

28" diagonal high-resolution green-phospher CRT (with 15level quantization) Effective diameter: 360 mm

2. Presentation Modes

Relative motion Head-up, North-up*, Course-up*, True motion North-up* (reset at 70% radius)

*Gyro interface GC-6 or gyro converter AD-100 required.

3. Range Scales and Range Ring Intervals

Range: 0.25, 0.5, 0.75, 1.5, 3, 6, 12, 24, 48, 120 nm Rings: 0.05, 0.1, 0.25, 0.25, 0.5, 1, 2, 4, 8,

4. Offcenter

50% radius of range scale in use

5. Minimum Range

25 m

6. Range Discrimination 20 m on 0.25 nm scale

7. Bearing Readout

By EBL, floating origin, 0.1° resolution

8. Accuracy

0.85% of range scale in use or Range: 7m, whichever is the greater

Bearing: EBL accuracy ±1°

9. Echo Plot

Manual entry, automatic calculation of CPA/TCPA/vector/course/ speed. Up to 10 targets being tracked can be marked with 10 different plot symbols such as circle, triangle, etc. with or without center dot. Automatically disabled when ARPA is activated.

10. Echo Trail

For radar and ARPA

11. Echo Average

Scan-to-scan correlation to improve detection in sea clutter

12. Guard Zone

Both inner and outer limits confined between 3 and Radius:

6 nm for N-type; free setting for Regular-type

Sector angle: 1-360° in any direction

Two Variable Range Markers switched (floating origin) 13. VRM 14. EBL

Two Electronic Bearing Lines switched (floating origin)

ARPA FUNCTIONS

1. Acquisition

Automatic mode: Automatic acquisition of up to 20 targets, plus manual acquisition of additional 20 targets. Manual mode:

Manual only acquisition of up to 40 targets

2. Suppression Areas

Three limit lines to define suppression areas in which automatic target acquisition will not occur. Each limit line, either fixed on land or fixed on ship, may be a single straight line or a string of lines containing up to 5 corners.

3. Acquisition Range 0.3 to 32 nm

4. Tracking Range: 0.2 to 32 nm, Speed: 99.9 knots max.

Vector Presentation

True or relative vectors switchable. Trend within 1 min., full accuracy within 3 min.

6. Vector Length

1 to 99 min. in steps of 1 min, front panel control

7. Past Positions

5, 10, 20 or 50 past positions of any targets being tracked at intervals of 15 or 30 s, 1, 2, 3, 6 or 12 min. (The number of plots and plot interval preset internally.)

8. Target Data Display

Range, bearing, course, speed, CPA, TCPA, BCR (bow crossing range) and BCT (time to BCR) of up to 3 targets

Course and speed

9. Own Ship Data Display

10. Alarms

Audible and visual alarms against threatening targets coming into the preset CPA/TCPA limits, lost targets, targets crossing guard rings. Visual alarm against system failure and target full situation.

11. Collision Warning

CPA limit: 0.2 to 10 nm

TCPA limit: 0 to 99 min.

12. Guard Rings

2 guard rings, 0.5 nm wide, between 0.7 and 32 nm, Sector 1-360° in any direction

13. Trial Maneuver

Simulates the effect on all tracked targets of an own ship maneuver without interrupting the updating of target information. Operator can change course, speed and delay time for simulation.

INTERFACING

1. Gyrocompass

Built-in interface accepts synchro signal (20-50 V, 50-400 Hz) or stepper signal (20-50 VDC, any polarity).

2. Speed Log

Contact closure or DC signal at 200, 400 or 500 pulses/nm.

External Radar

FAR-2800 series: Interface provided for one external radar. Interface provided for two external radars. FA-2800:

POWER SUPPLY

1. Display and Transceiver Units

110 VAC, 50/60 Hz, 1ø

Antenna Unit

220 VAC, 50 Hz, 1ø; 220 VAC, 60 Hz, 3ø; 380 VAC, 50 Hz, 3ø; 440 VAC, 60 Hz, 3ø

For the other input, optional transformer required, see connection diagram.

EQUIPMENT LIST

Standard Supply For FAR-2822/2830S 1. Display Unit 1 unit 2. Antenna Unit 1 unit 3. Standard Spare Parts 1 set 4. Installation Materials incl. 30m antenna cable 1 set

For FAR-2822X/2852X/2832S/2862S

Display Unit	1 unit
2. Antenna Unit	1 unit
3. Transceiver Unit	1 unit
Standard Spare Parts	1 set
5. Installation Materials incl. 30m antenna cable	1 set

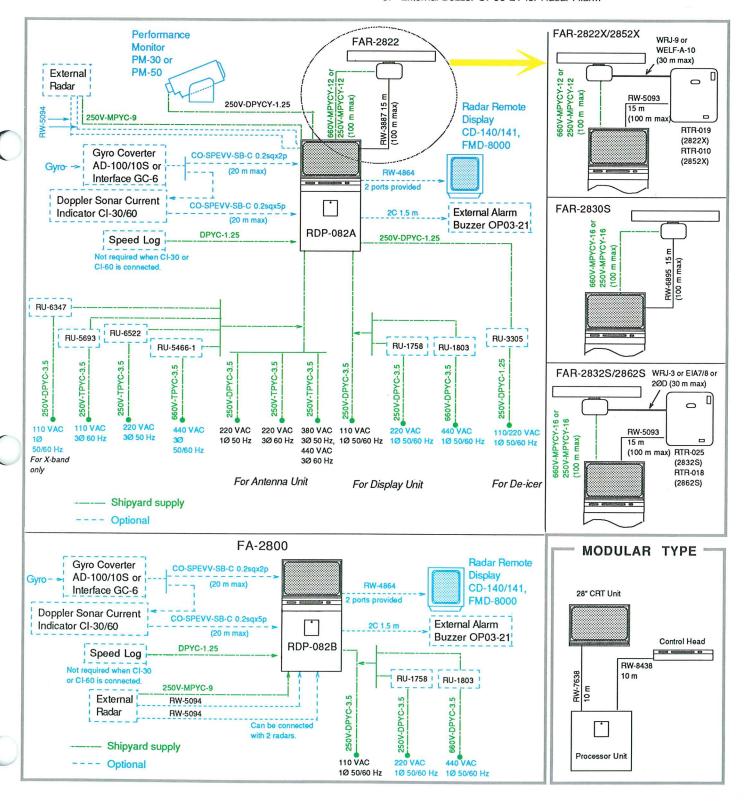
For FA-2800

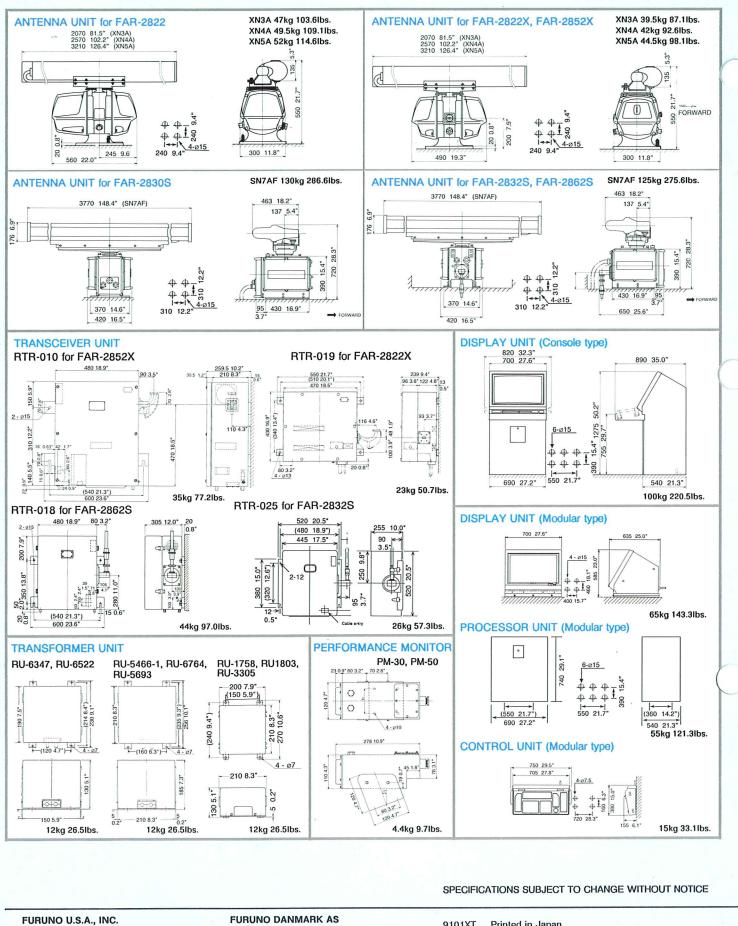
1. Display Unit 1 unit 2. Standard Spare Parts 1 set

For modular (separation) type, display unit is divided into CRT unit, control head and processor unit.

Optional

- Transformer
- 2. Performance Monitor PM-30 (X-band) or PM-50 (S-band)
- Remote Display CD-140, CD-141, GD-1400 or FMD-8000
- Gyro Interface GC-6 (built-in) or Gyro Converter AD-100 (or AD-10S) (external)
- Interswitch RJ-6 (built-in) 5.
- External Buzzer OP03-21 for Radar Alarm 6.





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